**Automated Traffic Signal** Performance Measures -The Fitbit<sub>®</sub> for **Your Signal** System

Date: April 27, 2017 Presented by: Susan Langdon



### Opportunity

There are approximately 400,000 signalized intersections in the US ~ we need a systematic procedure for identifying operational problems ... and fixing them using controller and probe data.



## How to Improve the Situation?



### How can we get useful data from the field?

How can we get useful information from the data?

How can we leverage information to improve signal operations?





### Pooled Fund Study

### Participants:

- Wisconsin DOT
- Indiana DOT
- Utah DOT
- City of Chicago
- Minnesota DOT
- California DOT
- New Hampshire DOT
- Texas DOT
- Mississippi DOT
- Georgia DOT
- Pennsylvania DOT
- USDOT





# Purdue University Research

Leader in research that has led to this ability along with partners

- Purdue, INDOT and controller manufacturers collaborate to develop data logging
- Purdue develops performance
  measures based on data
- UDOT develops software and website to utilize the data and performance measures

PERFORMANCE MEASURES FOR TRAFFIC SIGNAL SYSTEMS

An Outcome-Oriented Approach



Christopher M. Day, Darcy M. Bullock, Howell Li, Stephen M. Remias, Alexander M. Hainen, Richard S. Freije, Amanda L. Stevens, James R. Sturdevant, and Thomas M. Brennan



### High-Resolution Event Data Concept





# Controller Enumerations

### Event Code, Event Description, Parameter

### Active Phase Events:

- Phase On 0
- Phase Begin Green
- Phase Check
- 23 Phase Min Complete
- 45 Phase Gap Out
- Phase Max Out
- 6 Phase Force Off
- 7 Phase Green Termination
- 8 Phase Begin Yellow Clearance
- 9 Phase End Yellow Clearance
- 10 Phase Begin Red Clearance
- 11 Phase End Red Clearance

### Detector Events:

- 81 Detector Off
- 82 Detector On
- 83 Detector Restored
- 84 Detector Fault-Other
- 85 Detector Fault-Watchdog Fault
- 86 Detector Fault-Open Loop Fault

### Preemption Events:

- 101 Preempt Advance Warning Input
- 102 Preempt (Call) Input On
- 103 Preempt Gate Down Input Received
- Preempt (Call) Input Off 104
- 105 Preempt Entry Started



http://docs.lib.purdue.edu/jtrpdata/3/

### High Resolution Data

### **Detector 5 ON**

### Phase 2 BEGIN RED

### Phase 8 BEGIN GREEN

06/27/2013 01:29:51.1	10	8
06/27/2013 01:29:51.1	82	5
06/27/2013 01:29:52.2	1	2
06/27/2013 01:29:52.2	1	6
06/27/2013 01:29:52.3	82	2
06/27/2013 01:29:52.8	82	4
06/27/2013 01:29:52.9	81	4
06/27/2013 01:29:53.3	81	6
06/27/2013 01:29:54.5	81	2
06/27/2013 01:30:02.2	8	2
06/27/2013 01:30:02.2	8	6
06/27/2013 01:30:02.2	33	2
06/27/2013 01:30:02.2	33	6
06/27/2013 01:30:02.2	32	2
06/27/2013 01:30:02.2	32	6
06/27/2013 01:30:06.1	10	2
06/27/2013 01:30:06.1	10	6
06/27/2013 01:30:08.1	1	8
06/27/2013 01:30:13.1	32	8
06/27/2013 01:30:15.8	81	5
06/27/2013 01:30:18.5	82	6







# How Does It Work?





## System Requirements

- High-resolution data logging controller
- Detection
- Communication
- Server
- Website

### Does NOT require Central Traffic Management Software



## Types of Performance Measures

- Purdue Phase Termination
- Split Monitor
- Purdue Coordination Diagram
- Approach Delay
- Purdue Split Failure
- Purdue Link Pivot

- Pedestrian Delay
- Preemption Details
- Turning Movement Count
- Approach Volume
- Arrivals on Red
- Approach Speed
- Yellow and Red Actuations



### Phase Termination





## Split Monitor



US-89 2700 North SIG#5372 Phase 6 Wednesday, March 09, 2016 12:00 AM - Thursday, March 10, 2016 12:00 AM



### Purdue Split Failure

SplitFail

Avg. ROR

--- Percent Fails

GOR - GapOut

ROR - ForceOff

GOR - ForceOff
 ROR - GapOut

700 East @ 900 South - SIG#7184 Wednesday, April 27, 2016 12:00 AM - Wednesday, April 27, 2016 11:59 PM

#### Protected Phase 6: Southbound Thru



Total Split Failures = 93



### Purdue Coordination Diagram

Bangerter Hwy (SR-154) 2400 South Signal 7057 Phase: 2 Northbound Monday, March 14, 2016 12:00 AM - Monday, March 14, 2016 11:59 PM 78% AoG

Plan 1 Free Pla... Plan 7 Plan 13 Plan 7 Free Detector Activation 90% AoG 85% 91% AoG 45% AoG 90% AoG 82% 82% AoG - Change to Green 91% GT 65% GT 62% GT 58% GT 80% GT AoG... Ao ... Change to Yellow 0.99 PR 1.32 PR 0.78 PR 1.12 PR 1.05 1.1\_ 1.4 PR - Change to Red 23 02 05 12 13 20 21 22 — Volume Per Hour 00 01 03 04 06 07 08 09 10 11 14 15 16 17 18 19 AoG - Arrival On Green 2000 150 -GT - Green Time PR - Platoon Ratio 120--1500econds Volume Per Hour Arrivals during 90 green 1000 **Cycle Tim** 60 -500 30 Arrivals before green 0. 01 12 13 14 15 16 17 19 20 21 22 23 00 02 03 04 05 07 08 09 10 11 18

Time (Hour of Day)



### Approach Delay

State Street @ 7200 South - SIG#7168 Sunday, May 29, 2016 12:00 AM - Sunday, May 29, 2016 11:59 PM

#### Phase 2: Northbound

Average Delay Per Vehicle (AD) = 16 seconds; Total Delay For Selected Period (TD) = 91617 seconds



Simplified Approach Delay. Displays time between approach activation during the red phase and when the phase turns green. Does NOT account for start up delay, deceleration, or queue length that exceeds the detection zone.



### Arrivals on Red

Bangerter Hwy (SR-154) 5400 South (SR-173) Signal 7063 Overlap: 10 Northbound Thursday, March 07, 2013 12:00 AM - Thursday, March 07, 2013 11:59 PM

> Total Detector Hits = 18979 Total AoR = 6422 Percent AoR for the select period = 34



Arrivals on Red
 Percent Arrivals on Red
 Total Vehicles





Percent AoR

## Turning Movement Counts





## Red Light Monitoring



5600 West 2700 South Signal 7379 Phase: 4 Eastbound Monday, May 18, 2015 12:00 AM - Monday, May 18, 2015 11:59 PM



### Alerts

- Daily email at 7 am
- Uses Purdue Phase
  Termination chart data
- Flags phases with > 90% max-outs on each phase between 1 am and 5 am
- Compare to previous day's list; only phases with new flags are sent in email





Engineers can now directly measure what previously could only <u>estimate</u> and model



### What can Automated Signal Performance Measures do for you?

- Troubleshoot complaints and reduce wasted time for maintenance staff
- Identify problems more quickly without waiting for the complaint call
- Operate & optimize system more efficiently
- Retime signals as needed, not on a schedule
- Communicate system performance to public & agency leaders
- Transition from reactive management to proactive signal management
- Truly **MEASURE** system performance





# Future of Performance Measures?

- UDOT software is available on the FHWA Open Source Application Development Portal (OSADP) <u>http://www.itsforge.net</u>
- GDOT provided documentation for installation and use of the UDOT software
- Every Day Counts-4 Regional Summits late Fall 2016 ATSPMs major focus
  - <u>https://www.fhwa.dot.gov/innovation/everydaycounts/edc\_4/</u>
- FAST Act funding Advanced Transportation and Congestion Management Technologies Deployment <u>http://www.fhwa.dot.gov/fastact/factsheets/advtranscongmgmtfs.cfm</u>



## Questions?



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### Approach Speed

Bluff & 100 S, St. George, NB (5/5/2013)







### Approach Speed





### Offset Optimization Using Link Pivot Algorithm

https://www.youtube.com/watch?v=Yf1ZtDA8Edw





## Executive Reports & Prioritizing

Are signal operations improving, staying same or declining? By how much? How does agency most effectively priority resources and workload?

What are areas of most need?

Regional, corridor and intersection summaries available.



## System Requirements



- Econolite cobalt any version
- Econolite ASC3 v2.50+ & OS 1.14.03+
- Econolite 2070 with 1C CPU Module V32.50+
- Intelight Maxtime V 1.7.0+
- Peek ATC Greenwave 03.05.0528+
- Trafficware 980ATCV 76.10+
- Siemens M50 Linux & M60 ATC (ecom v 3.5+, NTCIP V4.5+)
- McCain ATC Omni eX 1.6+



### System Requirements Detection



Any detection will work - loops, pucks, video, radar.

Speed metric requires radar detection.



## System Requirements Communication



Can be accomplished in many ways, including fiber optic cable, wireless radio, cable or telephone providers, cell modem, satellite, twisted wire pair, even site visit to manually download.



System Requirements Operating Systems and Software



The software runs on Microsoft Windows Servers.

The database server is a Microsoft SQL 2008 or later; large systems will require Enterprise Edition.



System Requirements Storage and Processing Requirements



Detector data uses about 60% of the storage space, so the number of detectors attached to a controller will have a significant impact on the amount of storage space required.

Data storage will require approximately 12 MB per controller per day for 8 phase operation with detection on all approaches.



### System Requirements Website **Signal Performance Metrics**



Charts Reports Log Action Taken Links FAQ

->Signal Metrics



Version 3.1.5. Release Date: May 2016



### Purdue Travel Time





### Approach Volumes Stop Bar Detection

— Northbound

— Southbound --- Northbound D-Factor

--- Southbound D-Factor

2000 1800 0.9 1600 0.8 1400 0.7 Volume (Vehicles Per Hour) 1200 0.6 Directional Spli 1000 -0.5 800 -04 600 -0.3 400 -0.2200 -0.1 0 0 11 12 13 14 15 16 17 18 19 20 21 22 23 00 04 05 06 07 08 00 01 02 03 09 10 Time (Hour of Day)

Volume report for State Street 4500 South on the Northbound and Southbound approaches. 7/27/2016 12:00:00 AM - 7/27/2016 11:59:00 PM - Using Stop Bar Detection



### Approach Volumes Stop Bar and

Approach Detection



gort for State Street 4500 South on the Northbourd and Southbound approaches.	- 1 - 0.9 - 0.8 - 0.7 - 0.6 Directional Split - 0.5 Directional Split - 0.4 Directional Split - 0.3 - 0.2
	-0.3 -0.2 -0.1
12 03 04 05 06 07 08 09 10 11 12 13 14 15 16 17 18 19 20 21 22 23 00	•
Time (Hour of Day)	

Metric	Value	
Total Volume	11,440	
Peak Hour	7:45 AM - 8:45 AM	
Peak Hour Volume	891	
PHF	0.948	
Peak-Hour K-factor	0.0779	
<u> </u>		
Northbound Total Volume	11,440	
Northbound Peak Hour	7:45 AM - 8:45 AM	
Northbound Peak Hour Volume	891	
Northbound PHF	0.948	
Northbound Peak-Hour K-factor	0.0779	
Northbound Peak-Hour D-factor	NaN	
Southbound Total Volume	0	
Southbound Peak Hour	12:00 AM - 1:00 AM	
Southbound Peak Hour Volume	0	
Southbound PHF	0	
Southbound Peak-Hour K-factor	NaN	
Southbound Peak-Hour D-factor	0	

Metric	Value
Total Volume	31,156
Peak Hour	5:00 PM - 6:00 PM
Peak Hour Volume	2,711
PHF	0.948
Peak-Hour K-factor	0.087
Northbound Total Volume	18,544
Northbound Peak Hour	5:00 PM - 6:00 PM
Northbound Peak Hour Volume	1,488
Northbound PHF	0.964
Northbound Peak-Hour K-factor	0.0802
Northbound Peak-Hour D-factor	0.822
• • • • • • • • • • • • • • • • • • •	
Southbound Total Volume	12,612
Southbound Peak Hour	5:15 PM - 6:15 PM
Southbound Peak Hour Volume	1,226
Southbound PHF	1
Southbound Peak-Hour K-factor	0.0972
Southbound Peak-Hour D-factor	1.18



### Coordination: Progression Type

Metric: Approach Volume Metric Value Total Volume 47.646 One-way Peak Hour 5:00 PM - 6:00 PM 2400 Peak Hour Volume 3,561 2200 PHF 0.988 2000 Peak-Hour K-factor 0.0747 1800 Volume (Vehicles Per Hour) 1600 -Northbound Total Volume 24.634 1400 -Northbound Peak Hour 7:00 AM - 8:00 AM Northbound Peak Hour Volume 2,182 1200 -Northbound PHF 0.974 1000 Northbound Peak-Hour K-factor 0.0886 800 -Northbound Peak-Hour D-factor 0.491 600 -400 -Southbound Total Volume 23.012 Southbound Peak Hour 4:15 PM - 5:15 PM 200 -Southbound Peak Hour Volume 2.003 0 05 06 07 08 09 02 03 04 00 01 Southbound PHF Southbound Peak-Hour K-factor 0.087 Southbound Peak-Hour D-factor 0.701



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### **Link Pivot Algorithm**

 Based on the validated prediction methodology, we devised a way to systematically adjust offsets to find an optimal solution...



FIGURE 6 Performance of alternative mathodologies for offset optimization.

#### Computational Efficiency of Alternative Algorithms for Arterial Offset Optimization

BACKGROUND

Christopher M. Day and Darcy M. Bullock

This paper compares the performance of several algorithms for effort epitmization. A case study of a five-intervention priorial is presented. Cyclic probability distributions of solvicle arrivals and the probability of erven are need to characterilor traffic conditions ander alternative efforts. Five alcorithms for other optimization were selected for comparison musi-exhaustive sourch. Mante Carlo selection, emetic absorbitum, hill climiting, and the combination method. Each algorithm was evaluated with two alternative objectives: minimize delay and maximize vehicle pretty h on prees. The relative pretty manages of the objectifican wore obseactorized by the optimality of the solution that they returned, the number of exemption included to excente the absorithm, and the marginal real of adding an additional intersection to the system. All five algorithms effectively identified optimal or near-optimal offices within the solution space. 103 climbing was more efficient than practic algorithms, but the optimality of the substitute from both types was similar. The combination method found the most optimal afforts, with efficiency similar tarker of hill climiting. The conditioning method is recommended for arterial effect chainstein forware of its deterministic computational performance for identifying optimized offset timing plans.

The selection of offsets in traffic signal timing plans is critical forestablishing selacte progression. At present, mallie organeers rely on a rather small group of software programs for designing or adapting signal timing plans, which roly on their own internally hard-orded algorithms. Although there is a considerable literature comparing the performance of these software packages against each other and proposed methods, less actention has been puid to the relative performance of the internal algorithms. This paper explicitly considers the reviewmence of alternative algorithms in an alcotical traffic madel. Recently, the introduction of online data collection into reofficsignal controller fleroware has crabled signal events to be logged in real time at the highest possible time resolution (1). This paper doutlbes a methodology for offset optimization with high resultation controller data and compares the performance of alternative algorithms for optimizing offsets in that model. A causi-exhaustive search, Mone Carls selection, the combination method, hill climbing, and genetic algorithms (GAs) are compared. The paper conclusion with odation that the combination method be used to optimize offsets where possible because of its computational efficiency and robust performance.

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Transportation Research Research Journal of the Transportation Research Research No. 2005, Transportation Research Rated of the Nacional Journal of Washington, 21.0, 2011, pp. 27–47, 2013 - 10.13-01.20940-00

Office optimization can be described as a mathematical optimization weathlose in which the adjustable measurators are the officity and the objective is to minimize or maximize a performance measure that in a complex function of these parameters. In a network of a signals the number of possible offset combinations is generally (COPT), where C is the cycle length (c), and r is the resolution (c) of the search. The complexity of the problem increases experiorially with a making it occupital to adopt efficient optimization techniques. Table I lists elvantages and disabiantages of a viriety of mathematical technique for the offset optimization problem for delay minimization (14). The second system assess and Martin Carlo solution are having manerical strategies for sampling a large solution space. A quasiextractive search is an enumerative search using a value of e that makes (CP)<sup>1-1</sup> scenarios leasibly esculable. Morre Carlo selector another the solution space by random selection of parameter over many iterations. As more iterations are accumulated, the best toown parameter contribution continues to improve. However, no knowledge of the performance of not suggesteers is used to aid the relection of new attes. Heartistic optimization methods levenge the performance of past iterations. In this paper, full climbing and GAs are considered.

 In hill climbing, a vector of hill climb increments is applied to each offset the most optimal increment is returned (3). This is carried ast for one intersection at a time item iterative loop that repeats natil its system performance cannot be improved further.

\* To Gio, the promotion are cooled to genetic sequence and are manipated to a mission of the bottomic of DNA donate impositions (27). The first generation is a population of anotherly the second sequence of the second sequence of the second domatic second sequences, and an university of the second (20). For set of 10 first sequence of the second sequences of the cooled generation, which is presented by the second (20) of the set of 10 first sequence of the second sequences of the second sequences of the second second second second (20). For set of 10 first second sec

Transportation Research Record No. 2259, pp. 37-47, 2011

